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This manual describes the installation and connection of the E series controllers. This manual covers the installation, wiring and connection with external controller, devices and power. Please refer to Operation Manual and External I/O Manual for the operation of the controller.

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This manual describes the AS* language used in the Kawasaki Robot Controller E series. objective for this manual is to provide detailed information on the outline of the AS system, basic usages, data types, robot trajectory control and all the commands/instruction to allow effective usage of the AS system.

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